

RSV SchH3		Drive		Technique		Co-ordination		Rating	Max. Pts	Pts
1	Start + 1st part of 1st leg	willingness to work	balanced drive	take up of scent	take up into the track	without help	acc. of command		10	
		concentration	endurance	works confidently	consistency	conflict-free	tuning			
2 a	2nd part of 1st leg	willingness to work	balanced drive	take up into the leg	staying on the track	without help			10	
		concentration	endurance	goal orientation	consistency	conflict-free	tuning			
2 b	1st corner	willingness to work	balanced drive	acceptance of corner	works confidently	without help			5	
		concentration	endurance			conflict-free	tuning			
3 a	2nd leg	willingness to work	balanced drive	take up into the leg	staying on the track	without help			10	
		concentration	endurance	goal orientation	consistency	conflict-free	tuning			
3 b	2nd corner	willingness to work	balanced drive	acceptance of corner	works confidently	without help			5	
		concentration	endurance			conflict-free	tuning			
4 a	3rd leg	willingness to work	balanced drive	take up into the leg	stays on track	without help			10	
		concentration	endurance	goal orientation	consistency	conflict-free	tuning			
4 b	3rd corner	willingness to work	balanced drive	acceptance of corner	works confidently	without help			5	
		concentration	endurance			conflict-free	tuning			
5 a	4th leg	willingness to work	balanced drive	take up into the leg	stays on track	without help			10	
		concentration	endurance	goal orientation	steadiness	conflict-free	tuning			
5 b	4th corner	willingness to work	balanced drive	acceptance of corner	works confidently	without help			5	
		concentration	endurance			conflict-free	tuning			
6	5th leg	willingness to work	balanced drive	take up into the leg	stays on track	without help			9	
		concentration	endurance	goal orientation	consistency	conflict-free	tuning			
7	1st article	willingness to work	activity	indication	indicates / picks up	without help			7	
				position	until resuming track	conflict-free				
8	2nd article	willingness to work	activity	indication	indicates / picks up	without help			7	
				position	until resuming track	conflict-free				
9	3rd article	willingness to work	activity	indication	indicates / picks up	without help			7	
				position		conflict-free				
Total result A									100	

Start No. / Track No. / Track Layer			
Total performance			
Add'l. information	Withdrawn/disqualified due to		
Weather conditions	difficult	medium	easy
Track laying	difficult	medium	easy
Surface	difficult	medium	easy
Temperament test			
passed		failed	

Pkt	V	SG	G	B	M
5	4,8	4,5	4,0	3,5	3,4 - 0
7	6,7	6,3	5,6	4,9	4,8 - 0
9	8,6	8,1	7,2	6,3	6,2 - 0
10	9,6	9,0	8,0	7,0	6,9 - 0
100	96	90	80	70	69,9 - 0

place/date
dog handler
dog name
litter day
ID/tattoo
judge

place/date

dog name

ID/tattoo

Pkt	V	SG	G	B	M
10	9,6	9,0	8,0	7,0	6,9 - 0
15	14,4	13,5	12,0	10,5	10,4 - 0
100	96	90	80	70	69,9 - 0

Start No.



RSV/SchH3		Drive		Technique			Co-ordination		Rating	Max. Pts	Pts
1	Free heeling	willingness to work	activity	basic position	straight/position	gun shot	acceptance of signals	without help	10		
		endurance		about turn	change of pace	right corner	synchronisation	concentration			
				right corner	about turn	stop					
				left corner	group	stop					
2	Sit out of motion	willingness to work	activity	basic position	development	command	acceptance of signals	without help	10		
				execution	holds position	handler return	conflict free	concentration			
3	Down out of motion with recall	willingness to work	activity	basic position	development	command	acceptance of signals	without help	10		
		dynamics		execution	holds position	approach	conflict free	concentration			
				front	finish						
4	Stand while running	willingness to work	activity	basic position	development	command	acceptance of signals	without help	10		
		dynamics		execution	holds position	approach	conflict free	concentration			
				front	finish						
5	Retrieve on flat	willingness to work	activity	basic position	run	pick up	acceptance of signals	without help	10		
		dynamics		return	front	hold	conflict free	concentration			
				release	finish						
6	Bring over 1 m hurdle	willingness to work	activity	basic position	run	jump	acceptance of signals	without help	15		
		dynamics		pick up	return	return jump	conflict free	concentration			
				front	hold	release					
				finish							
7	Bring over A-frame	willingness to work	activity	basic position	run	jump	acceptance of signals	without help	15		
		dynamics		pick up	return	return jump	conflict free	concentration			
				front	hold	release					
				finish							
8	Send-out	willingness to work	activity	basic position	development	send-out	acceptance of signals	without help	10		
		dynamics		drop	remain	sits	conflict free	concentration			
9	Long down under distraction	willingness to work	calm	basic position	down	gun shot	acceptance of signals	without help	10		
		balanced drive		remain	sits		conflict free	concentration			
Total result B									100		

dog handler

litter day

judge

B

place/date

dog name

Pkt	V	SG	G	B	M
5	4,8	4,5	4,0	3,5	3,4 - 0
10	9,6	9,0	8,0	7,0	6,9 - 0
15	14,4	13,5	12,0	10,5	10,4 - 0
20	19,2	18,0	16,0	14,0	13,9 - 0
100	96	90	80	70	69,9 - 0

ID/tattoo

dog handler

judge

litter day



RSV SchH3		Drive		Technique			Co-ordination		Rating	Max. Pts	Pts
1	Blind Search	dynamics		basic position	1st blind	cross-over	timing commands	acceptance of signals	10		
				2nd blind	cross-over	3rd blind	turn on command	contact to handler			
				cross-over	4th blind	cross-over					
				5th blind	cross-over	6th blind					
2	Hold and Bark	endurance	dominance	drive switching	barking	hold	independence	stress free approach	10		
				approach	change obedience	basic position	obedience phases on command	without help			
3	Pre-vention of escape	lead-in	grip impact	free heeling	down / giving free	fulness of grip	obedience phases on command	conflict-free biddability	10		
		grip firmness	dominance	finish	drive switching	guarding	release on command	without help			
4	De-fense while Guarding	attack	grip impact	fulness of grip	end phase	drive switching	obedience phases on command	firm approach	20		
		grip firmness	dominance	guarding	step by		release on command				
5	Back Transport	eagerness	tension	basic position	heel without leash	distance	obedience phases on command	conflict-free biddability	5		
		self control						without help			
6	Attack	attack	grip impact	fulness of grip	end phase	drive change	obedience phases on command	firm approach	15		
		grip firmness	dominance	guarding	approach	end phase	release on command	conflict-free biddability			
				side transport							
7	Attack out of Motion	dynamics		obedience	basic position	fulness of grip		attack on command	10		
		attack	grip impact								
		grip firmness		end phase	drive switching	guarding	release on command	conflict-free biddability			
8	Defen-se of Attack	attack	grip impact	fulness of grip	end phase	drive switching	obedience phases on command	firm approach	20		
		grip firmness	dominance	guarding	approach	end phase	release on command				
				side transport							
TSB: pronounced <input type="checkbox"/>		present <input type="checkbox"/>	insufficient <input type="checkbox"/>	Total result C					100		

Start No.:

Helper work

hard

normal

light

Total result

A	
B	

C

Pts/ Rating