R	SVSchH2		Orive	Tec	hnique	Со-о	ordination	Rating	Max. Pts	Pts				1	
	Start + 1st	willingness to work	balanced drive	take up of scent	take up into the track	without help	acc. of command				Start No.	. / Trac	k No./		qS aye
1	part of 1st leg	concentration	endurance	works confidently	consistency	conflict-free	tuning		20						
											Total pe	rforma	nce		
	0.11.6	willingness to work	balanced drive	take up into the leg	staying on the track	without help					Add'l. in	formati	on	Withdraw	vn/
2 a	2nd part of 1st leg	concentration	endurance	goal orientation	consistency	conflict-free	tuning		15		Weather	condit	ions	difficult	_
											Track lay			difficult	\dagger
		willingness to work	balanced drive	acceptance of corner	works confidently	without help					Surface	, <u>9</u>		difficult	
2 b	1st corner	concentration	endurance			conflict-free	tuning	10			Temperament test				
											passed				
		willingness to work	balanced drive	take up into the leg	staying on the track	without help					Pkt 9	V 8,6	SG 8,1	G 7,2	
3 a	2nd leg	concentration	endurance	goal orientation	consistency	conflict-free	tuning		15		10	9,6	9,0	8,0	T
											11	10,6	9,9	8,8	\perp
		willingness to work	balanced drive	acceptance of corner	works confidently	without help					15 20	14,4 19,2	13,5 18,0	12,0 16,0	
3 b	2nd corner	concentration	endurance			conflict-free	tuning		10		100	96	90	80	
		willingness to work	balanced drive	take up into the leg	stays on track	without help						e/dat			
4	3rd leg	concentration	endurance	goal orientation	consistency	conflict-free	tuning		9		dog	hand	ler		
											dog	name	Э		
		willingness to work	activity	indication	indicates / picks up	without help					litter	day			
5	1st article			position	until resuming track	conflict-free			11		ID/ta	•			
											וטונם	แเบบ			
		willingness to work	activity	indication	indicates / picks up	without help					judg	е			
6	2nd article			position		conflict-free			10						
							Total result A		100						



Start No. / Track No.	/ Track Lay	er						
Total performance								
Add'l. information	Withdrawn/disqualified due to							
Weather conditions	difficult	medium	easy					
Track laying	difficult	medium	easy					
Surface	difficult	medium	easy					

Pkt	V	SG	G	В	M
9	8,6	8,1	7,2	6,8	6,2 - 0
10	9,6	9,0	8,0	7,0	6,9 - 0
11	10,6	9,9	8,8	7,7	7,6 - 0
15	14,4	13,5	12,0	10,5	10,4 - 0
20	19,2	18,0	16,0	14,0	13,9 - 0
100	96	90	80	70	69,9 - 0

failed

Pkt	٧	SG	G	В	М
10	9,6	9,0	8,0	7,0	6,9 - 0
15	14,4	13,5	12,0	10,5	10,4 - 0

ID/tattoo

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SVSchH2	Dr	ive		Technique	100 96 90 80 70	69,9 - 0 Co-or 0	lination	Rating	Max. Pts	A
	willingness to work	activity	basic position	straight/position	gun shot	acceptance of signals	without help			
Free hee-	endurance		about turn	change of pace	right corner	synchronisation	concentration			RSV2000
			right corner	about turn	stop				10	Start No.:
9			left corner	group	stop					
	willingness to work	activity	basic position	development	command	acceptance of signals	without help			
Sit out of motion			execution	holds position	handler return	conflict free	concentration		10	
motion										
Down out	willingness to work	activity	basic position	development	command	acceptance of signals	without help			
	dynamics		execution	holds position	approach	conflict free	concentration			place/dat
of motion with recall			front	finish					10	
				•	·					dog hand
	willingness to work	activity	basic position	development	command	acceptance of signals	without help			
Stand while	,		execution	holds position	handler return	conflict free	concentration	-		
running			finish						10	
	willingness to work	activity	basic position	run	pick up	acceptance of signals	without help			littor day
Retrieve on	dynamica		return	front	hold	conflict free	concentration			litter day
flat			release	finish					10	
	willingness to work	activity	basic position	run	jump	acceptance of signals	without help			
	dynamics		pick up	return	return jump	conflict free	concentration			
Bring over 1 m hurdle			front	hold	release				15	judge
T III II II II II			finish							
	willingness to work	activity	basic position	run	jump	acceptance of signals	without help			
	dynamics		pick up	return	return jump	conflict free	concentration			
Bring over A-frame			front	hold	release				15	
A-irailie			finish							
				•						
	willingness to work	activity	basic position	development	send-out	acceptance of signals	without help			
Send-out	dynamics		drop	remain	sits	conflict free	concentration		10	
Long down	willingness to work	calm	basic position	down	gun shot	acceptance of signals	without help			
Long down under dis-	balanced drive		remain	sits		conflict free	concentration]	10	
traction										

place/date	dog name	ID/tattoo

dog handler litter day judge

Pkt	٧	SG	G	В	M
5	4,8	4,5	4,0	3,5	3,4 - 0
10	9,6	9,0	8,0	7,0	6,9 - 0
20	19,2	18,0	16,0	14,0	13,9 -0
30	28,8	27	24,0	21,0	20,9 - 0
100	96	90	80	70	0



		I						100 96 90 80 70 0				
RS	SVSchH2	D	rive		Technique		Co	o-ordination	Ra- ting.	Max. Pts	Pts	^
		dynamics		basic position	1st blind	cross-over	timing commands	acceptance of signals				RSV2000
	Blind			2nd blind	cross-over	3rd blind	turn on command	contact to handler		5		H345995
'	Search			cross-over	4th blind					5		Start No.:
												Otal Citon
				drive switching	barking	hold	independence	stress free approach				
	Hold and	endurance	dominance	approach	change	basic position	obedience phases	without help				
	Bark				obedience		on command			10		
		lead-in	grip impact	free heeling	down / giving free	fulness of grip	obedience phases	conflict-free biddability				Helper work
	Prevention	i 6	4	finish	dai a sa italaisa	and a	on command	with and bala		10		hard
	of escape	grip firmness	dominance	TINISN	drive switching	guarding	release on command	without help				normal
4				fulness of min	and above	datus suitabis s	ahadianan ahana	firm conversely				light
	Defense	attack	grip impact	fulness of grip	end phase	drive switching	obedience phases on command	firm approach				
	while Guar- ding	grip firmness	dominance	guarding	step by		release on command			20		
	ding											
		eagerness	tension	basic position	heel without leash	distance	obedience phases on command	conflict-free biddability		5		
	Back Transport	self control						without help				
		attack	grip impact	fulness of grip	end phase	drive change	obedience phases on command	firm approach				
	Attack	grip firmness	dominance	guarding	approach	end phase	release on command	conflict-free biddability		30		
				side transport								
		dynamics	attack	obedience	basic position	fulness of grip		attack on command				
	Attack out	grip impact	grip firmness	end phase	drive switching	guarding		firm approach				Total result
•	of Motion		·	approach	end phase	side transport	release on command	conflict-free biddability	1	20		A
					<u>'</u>	,						В
												С
SI	B: pronounced	pre	esent	insufficient				Total result C		100		Pts Rating