												8,6 9,6 10,6	8,1 9,0 9,9	7,2 8,0 8,8	7,0	6,2 - 0 6,9 - 0 7,6 - 0	A
RSVSchH1		Drive		Technique		Co-ordination		Rating	Max. Pts	Pts		14,4	13,5	12,0		10,4 - 0	
	Start + 1st part of 1st leg	willingness to work	balanced drive	take up of scent	take up into the track	without help	acc. of command				100	19,2 96	18,0 90	16,0 80		13,9 - 0 69,9 - 0	RSV200
1		concentration	endurance	works confidently	consistency	conflict-free	tuning		20		Start N	0.71		0.71	ack Lay		
		willingness to work	balanced drive	take up into the leg	staying on the track	without help					Total	perfo	rmano	e			
	2nd part of 1st leg	concentration	endurance	goal orientation	consistency	conflict-free	tuning		15		Add'l.	inforr	nation	V	Vithdraw	n/disqua	alified due to
	1st corner	willingness to work	balanced drive	acceptance of corner	works confidently	without help					Weather conditions difficult medium Track laying difficult medium						
2 b		concentration	endurance			conflict-free	tuning		10		Surfac		9		ifficult	mediu	
	2nd leg	willingness to work	balanced drive	take up into the leg	staying on the track	without help					Tempe	rame	nt tes	İ			🖂
3 a		concentration	endurance	goal orientation	consistency	conflict-free	tuning		15		passed	L				fa	iled
_		willingness to	balanced drive	acceptance of corner	works confidently	without help					pla	ce/c	late				
3	2nd corner	work concentration	endurance			conflict-free	tuning	_	10		dog handler						
											dog	ına	me				
		willingness to work	balanced drive	take up into the leg	stays on track	without help					litte						
4	3rd leg	concentration	endurance	goal orientation	consistency	conflict-free	tuning		9		ID/1						
_		willingness to work	activity	indication	indicates / picks up	without help					jud						
5	1st article			position	until resuming track	conflict-free		_	11			-					
	2nd article	willingness to	activity	indication	indicates / picks up	without help											
6		work		position		conflict-free		_	10								
							Total result A		100								

Pkt	V	SG	G	в	М
10	9,6	9,0	8,0	7,0	6,9 - 0
15	14,4	13,5	12,0	10,5	10,4 - 0
20	19,2	18,0	16,0	14,0	13,9 - 0



					20 19,2 18,0 16,0 14,0 13,9-0						1	
RS	VSchH1	D	rive		Technique	100 96 90 80	70 69,9 - 0 Co-orc	lination	Rating	Max. Pts	Pts	A
		willingness to work	activity	basic position	straight/position	gun shot	acceptance of signals	without help				2
		endurance		about turn	change of pace	right corner	synchronisation	concentration				RSV2000
1	Free hee- ling			right corner	about turn	stop				20		Start No.:
	Ū			left corner	group	stop						Start NO
	Sit out of motion	willingness to work	activity	basic position	development	command	acceptance of signals	without help				
2				execution	holds position	handler return	conflict free	concentration	10			
		willingness to work	activity	basic position	development	command	acceptance of signals	without help				
_	Down out	dynamics		execution	holds position	approach	conflict free	concentration		10		
3	of motion with recall			front	finish					10		place/date
												place/date
		willingness to work	activity	basic position	run	pick up	acceptance of signals	without help				1
	Retrieve on	dynamics		return	front	hold	conflict free	concentration				dog handler
4	flat		1	release	finish					10		
					1							
		willingness to work	activity	basic position	run	jump	acceptance of signals	without help				dog name
		dynamics		pick up	return	return jump	conflict free	concentration				
5	Bring over 1 m hurdle			front	hold	release			15			litter day
	i in nurule			finish			-					
					1							
		willingness to work	activity	basic position	run	jump	acceptance of signals	without help				ID/tattoo
		dynamics		pick up	return	return jump	conflict free	concentration				
6	Bring over front hold	hold	release				15		judge			
	A-II aille			finish		1	1					,
		willingness to work	activity	basic position	development	send-out	acceptance of signals	without help				
7	Send-out	dynamics		drop	remain	sits	conflict free	concentration		10		
					1							
		willingness to work	calm	basic position	down	gun shot	acceptance of signals	without help				
8	Long down under distrac-	balanced drive		remain	sits		conflict free	concentration		10		
	tion				I							
	1							Total result B		100		-
								iotai result B		100		J





С

RSVSchH1		Drive			Technique		Co-ord	Co-ordination			90 Pts 35	28,8 27,0 24,0 21,0 20 33,6 31,5 28,0 24,5 24
	Blind Search	dynamics		basic position	1st blind	cross-over	timing commands	acceptance of signals			100	96 90 80 70 69,
1				2nd blind			turn on command	contact to handler		5		Start No.:
				`								
	Hold and Bark	endurance	dominance	drive switching	barking	hold	obedience phases on command	stress free approach				
2				approach / calling	change obedience	basic position	independence	without help		10		Helper work
												normal light
	Prevention of escape	lead-in	dominance	free heeling	down / giving free	fulness of grip	obedience phases on command	conflict-free biddability				place/date
3		grip impact	grip firmness	finish	drive switching	guarding	release on command	without help		20		dog handler
												dog name
		attack	dominance	fulness of grip	end phase	drive switching	obedience phases on command	firm approach				litter day
4	Defense while Guar- ding	grip impact	grip firmness	guarding	step by		release on command			35		·
												ID/tattoo
		dominance	attack	obedience	basic position	fulness of grip		conflict-free biddability				judge
5	Attack out of Motion	grip impact	grip firmness	end phase	drive switching	guarding		stress free approach		30		Total result
				approach	end phase	side transport	release on command	attack on command				В
										C Pts Rating		
TS	TSB: pronounced present insufficient Total result C									100		

Triebverhalten = Expression of drive, Selbstsicherheit = Self-confidence, Belastbarkeit = Ability to withstand stress